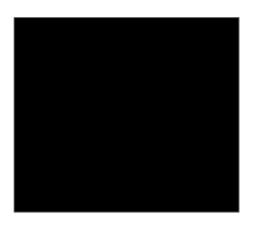
RL Algorithms Are Misbehaved Black Boxes

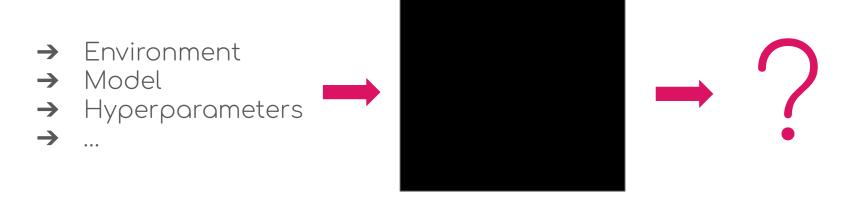
Theresa Eimer



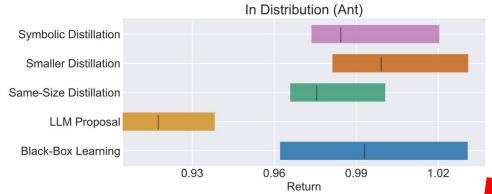
What is a Black Box and Why Would I Care?



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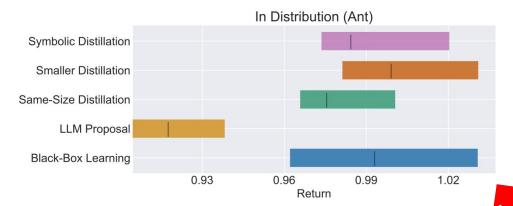


Meta-Learning Algorithms [Goldie et al. 2025]

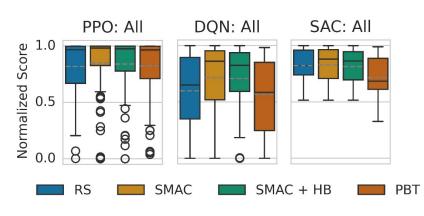




Meta-Learning Algorithms [Goldie et al. 2025]



HPO [Becktepe & Dierkes et al. 2024]



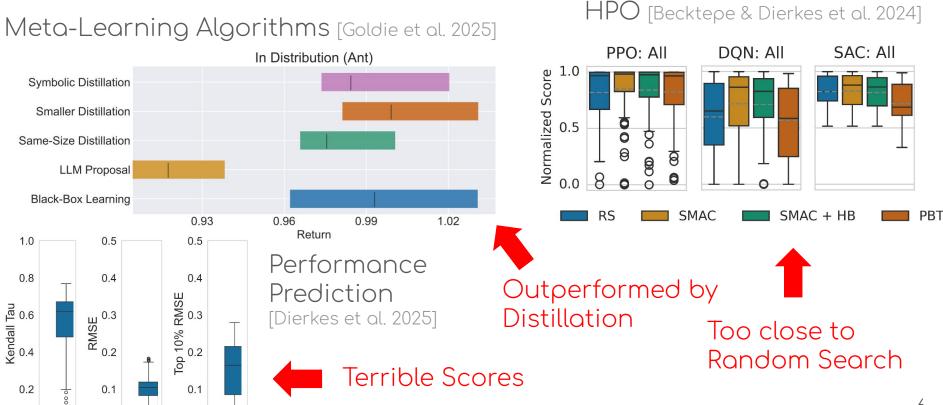
Outperformed by Distillation

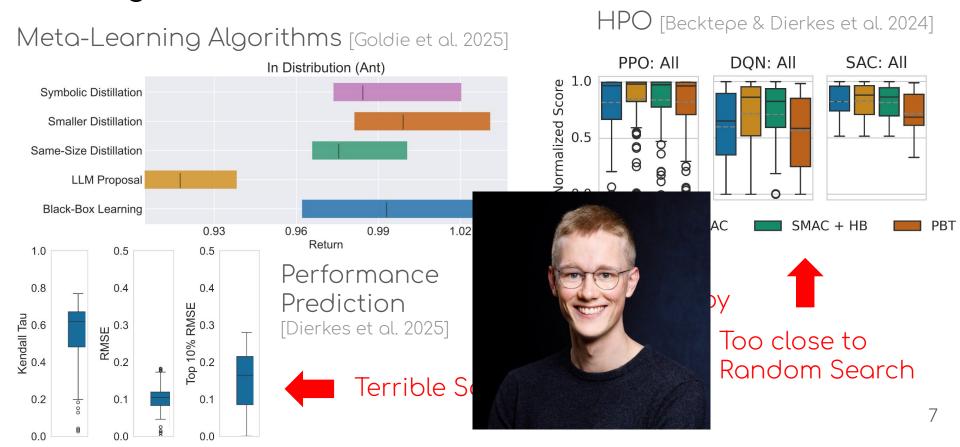


Random Search

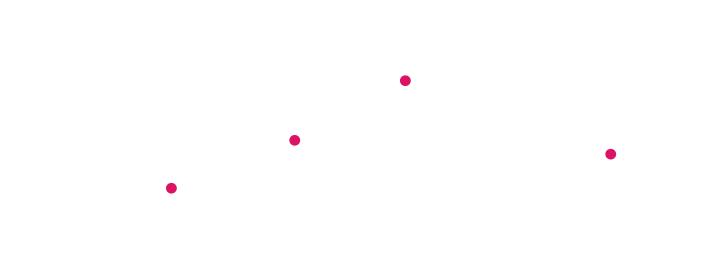
0.0

0.0

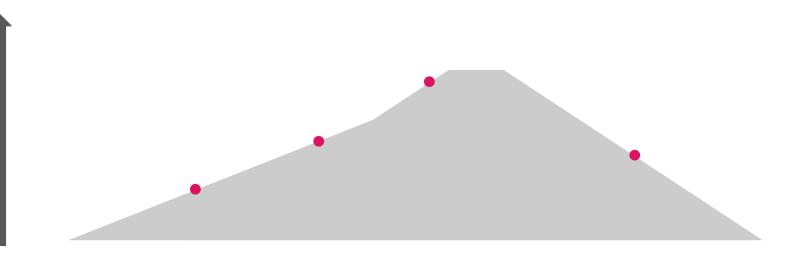




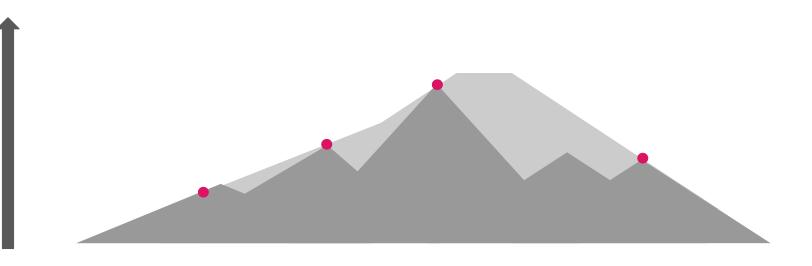
Explanation Attempt 1: Rugged Landscapes?



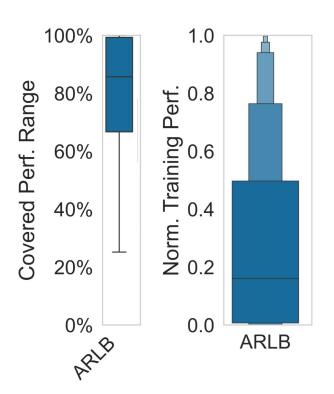
Explanation Attempt 1: Rugged Landscapes?



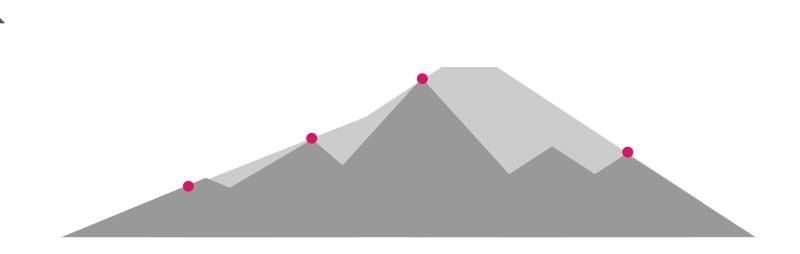
Explanation Attempt 1: Rugged Landscapes?

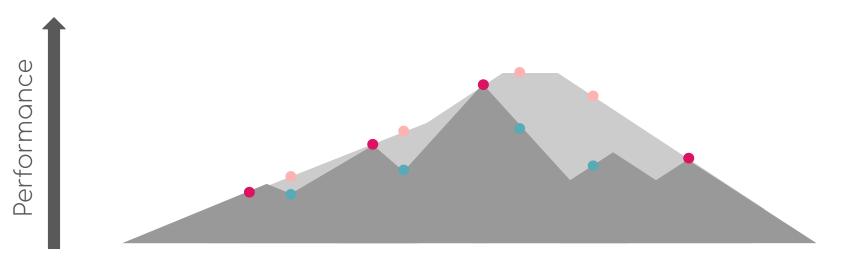


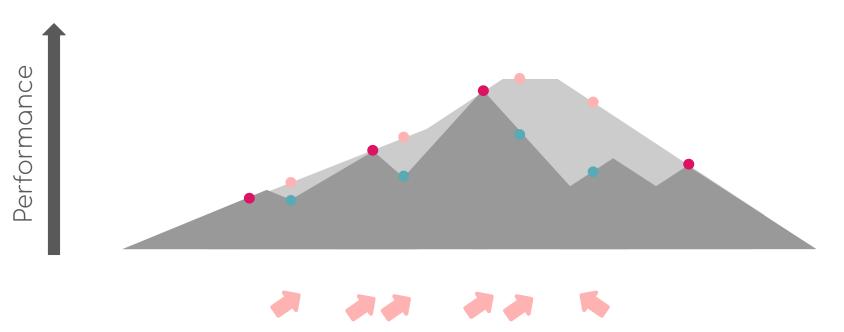
Performance Across Hyperparameters

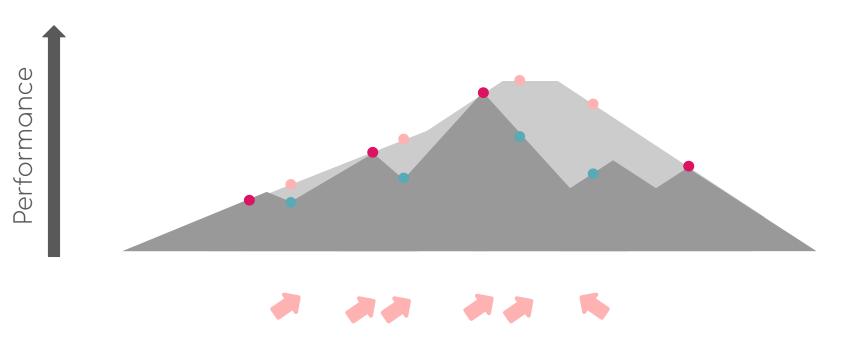


- → ARLBench [Becktepe & Dierkes et al. 2024] Dataset
- → DQN, PPO and SAC
- → 21 Environments in total
- → 256 randomly sampled hyperparameter configurations
- → 10 seeds

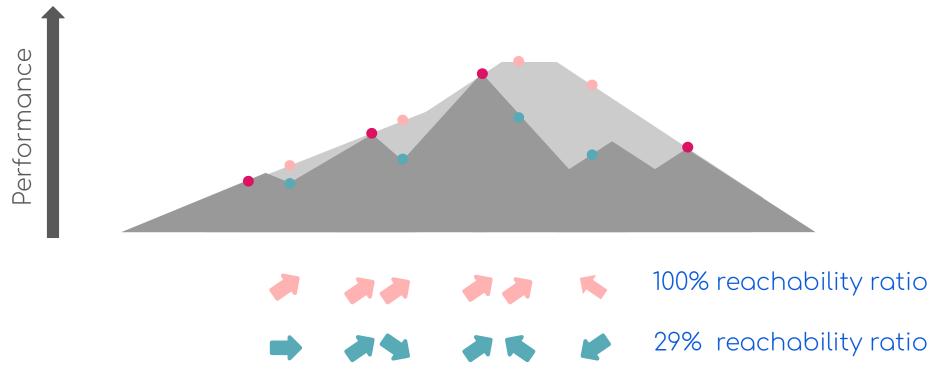




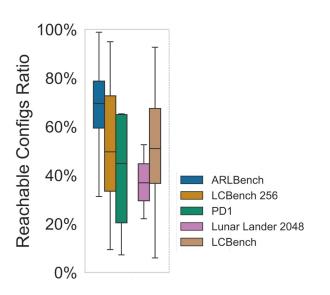




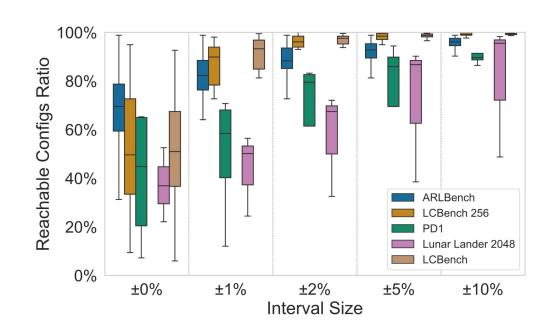
We can reach the optimum from every point with an increasing path!



- → ARLBench: RL Data
- → LCBench [Zimmer et al. 2021]: supervised learning for tabular data
- → PD1 [Wang et al. 2024]: supervised learning for computer vision
- → LunarLander 2048: larger PPO on LunarLander dataset



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LCBench

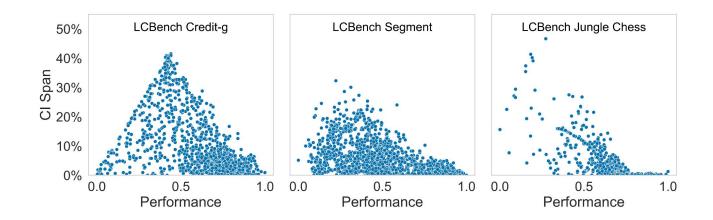


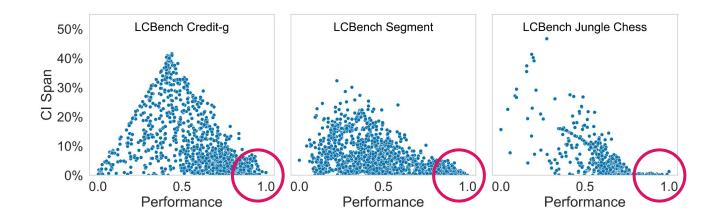
LCBench

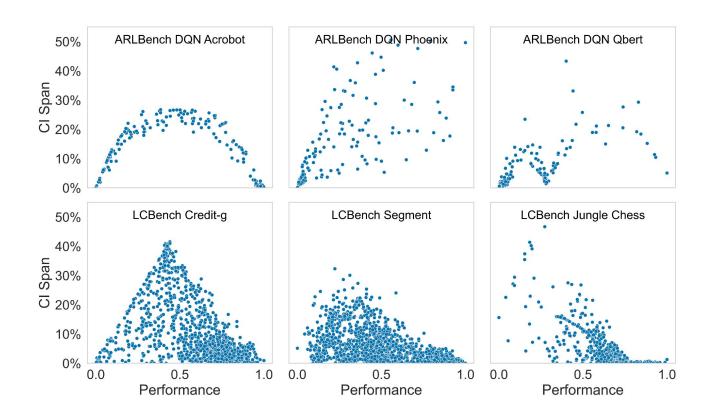


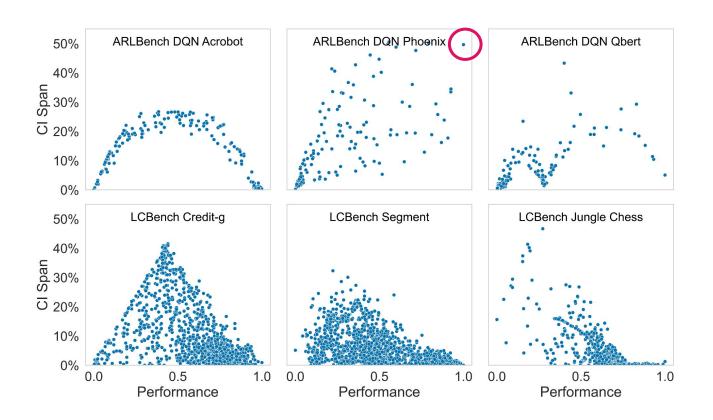
LCBench ARLBench

LCBench ARLBench





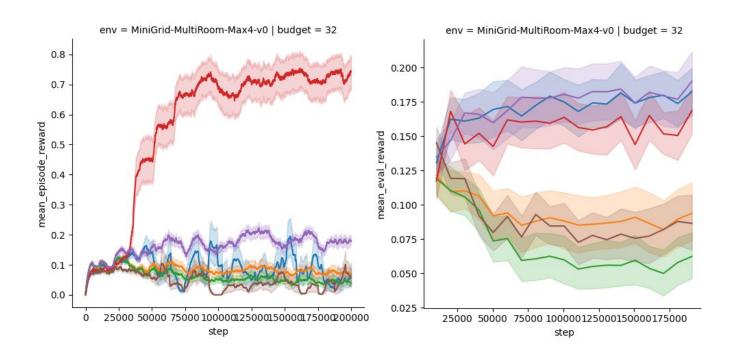




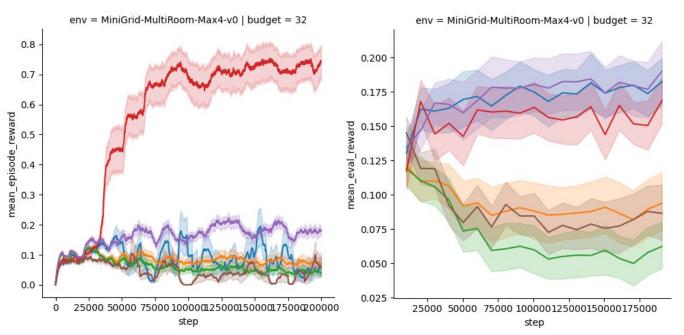
The RL Performance Landscape

- → Bottom-heavy performance distribution
- → Tendency towards fewer, but large landscape features
- → Inconsistent, hard-to-model deviations between runs

The Good News: It's Free!



The Good News: It's Free!



- 1. HPO
- 2. Training Across Seeds
- 3. Evaluation

The Good News: It's Free!

