



DAC - Dynamic Algorithm Configuration





What is DAC?

- DAC is an algorithm configuration paradigm
- Task: find the best hyperparameter value for each instance **at each timestep**
- Goal: increase algorithm performance and efficiency
- Generalization of Algorithm Configuration (AC) and Per-Instance Algorithm Configuration (PIAC)
- Can be modelled as a sequential decision making problem



Why Configure Dynamically?

AC tools are already good at finding suitable hyperparameter configurations, But:

- In many algorithms, the role of hyperparameters shift during training
 Example: exploration hyperparameters in RL
- Optimal hyperparameter values can correspond to the algorithm's progress
 Example: learning rate in ML algorithms
- Both of these can vary between instances
 Example: CNN on MNIST or on ImageNet



- Three disciplines, each with its own equipment
- Goal: fastest time possible
- Disciplines: Swimming, Running, Biking
- Equipment: 🗠 🚲 🖨



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- While their order is fixed, the length of each discipline can vary
- Thus: there's no one-size-fits all solutions
- Different triathlons can only be solved by accounting for their length
- Each triathlon length in this example is an **instance** of a triathlon
- We can also imagine future instances with different orders of the disciplines or even repeating disciplines



Dynamic Configuration in Machine Learning

- Initially: high learning rate to efficiently traverse loss landscape
- Once minimum is found: decrease learning rate to continue descending
- Possibly helpful: learning rate spikes during training to find global minimum

TODO: make plots for this



Overview

- 1. What is DAC?
- 2. Example: AC solvers for DAC
- 3. Example: DAC by Reinforcement Learning
- 4. The State of DAC & Open Questions



DAC Defined

Given:

- An algorithm \mathcal{A} with configuration space Θ
- A distribution ${\mathcal D}$ over a target problem instances with domain J
- A space of dynamic configuration policies Π with $\pi: \mathcal{S} \times \mathcal{I} \rightarrow \Theta$
- A cost metric c: $\Pi \times \mathcal{I} \rightarrow R$

Find $\pi^* \in \operatorname{argmin}_{\pi \in \Pi} E_{\hat{r} \mathcal{D}} c(\pi, t)$ [Adriaensen et al. 2022]



DAC In Practice





AC Solvers for DAC

- DAC can be solved using classical AC solvers
- Idea: search for a hyperparameter per pre-set time interval
- Downside: tradeoff between number of intervals and search space size
- Upside: there are fairly sophisticated AC solvers that perform very well on many different tasks



Example: SMAC for Dynamic Learning Rates

- Setting: a set of different CNNs on MNIST and CIFAR10
- Task: control the learning rate to minimize prediction error
- SMAC [Lindauer et al. 2022] with Bayesian Optimization and Hyperband is used
- DAC outperforms the best static learning rate in almost all cases [Adriaensen et al. 2022]



Figure: SMAC (dark blue solid) and static LR values on different optimizers



DAC by Reinforcement Learning

- As DAC can be modelled as a sequential decision problem, we can solve it using Reinforcement Learning
- Each action the agent takes changes the hyperparameter
- Downside: RL is often unreliable, scaling to multiple hyperparameters is hard
- Upside: search space is independent of the number of hyperparameter changes, generalization can be easier than with classical AC solvers



Example: GPS for CMA-ES

- Setting: CMA-ES of different functions
- Task: control the step size to minimize the current function
- RL agent learns from dynamic standard heuristic using GPS [Levine & Koltun 2013]
- While DAC needs training time, it beats even the static oracle [Adriaensen et al. 2022]



Figure: DAC and static configuration variants on CMA-ES



State of the DAC

- Several successful applications of DAC
- Dedicated benchmark library from different domains [Eimer et al. 2020]
- On-going research into better solutions methods
- Collaborative efforts to expand both available problems and solutions
- What's next?



The DAC4AutoML Competition Setting

- Competition for the AutoML-Conf 2022
- Two tracks: DAC for ML and DAC for RL
- Motivation: create a problem setting that reflects interesting ML and RL configuration problems
- Focus on generalization across several different instance options
- Task: beat both static baselines and well-known dynamic heuristics



The DAC4AutoML Competition Setting - DAC4SGD

- Image Classification on different image datasets, hyperparameter configurations and architectures
- Task: dynamic learning rate control across variations
- Test entropy loss is used for scoring
- Baselines: Static learning rate, cosine annealing [Loshchilov & Hutter 2017], reduce learning rate on plateau [Pytorch; Paszke et al. 2019]
- Results: two participants beat all baselines, all beat the static one



The DAC4AutoML Competition Setting - DAC4RL

- Training an RL agent each for 5 different environments with variations
- Task: controlling the algorithm and all its hyperparameters
- Rank across environments is used for scoring
- Baselines: SB3 Zoo optimized hyperparameters [Raffin et al. 2021], PB2 on the competition setting [Parker-Holder et al. 2020]
- Results: one participant could beat all baselines, setting overall is hard



Current Open Questions

- How can we scale to more hyperparameters?
- Is there a best DAC method? Can we combine existing ones?
- What are ways to bootstrap from existing solutions?
- How far can we push generalization in DAC for ML?



If You Want To Know More

- Find all our research on DAC on automl.org
- Read our recent <u>overview paper</u> on DAC
- Get started working on DAC with <u>DACBench</u>
- Get in touch!



Bibliography

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Image Sources

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