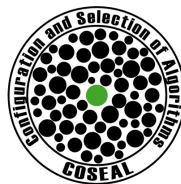
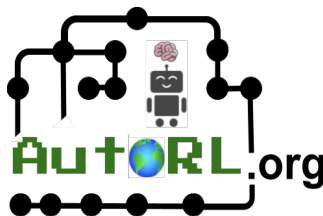


Is My RL Algorithm a Good Tool?

What Evaluation Strategies Tell Us About Our Algorithms

Theresa Eimer



Goals of Evaluations

1. Support research contributions
 2. Show gaps in our knowledge (e.g. theory - practice mismatches)
 3. Provide a basis for transferring research into application
 4. ...
- N. Enable future research progress

Current practice (In Empirical Online RL)

- Select algorithm(s) to evaluate
- Select meaningful environment(s) to evaluate on
- Set evaluation settings
- Set hyperparameters
- Perform several runs to account for randomness
- Compare mean reward or return over time

What Could “Better” Look Like?

- Select algorithm(s) to evaluate
- Select widespread community-driven benchmark for research question

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- Select widespread community-driven benchmark for research question
- Use benchmark evaluation settings
- Set hyperparameters using standardized process
- Perform several runs to account for randomness as prescribed by benchmark
- Compare benchmark metrics in statistical test

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Application specialist: “I want to know which algorithm solves my exact task setting”

Translation: evaluation environment is fixed, algorithm can be freely specified, often budget is limited

Evaluation should show:

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Evaluation should show:

→ Algorithm & all settings transfer between related problems

Zero-shot transfer of algorithm & training settings within domain

→ Algorithm & settings can be very efficiently adapted to changes in the setting

Tunability values for very low-budget tuning

Excursion: Tunability [Probst et al. 2019]

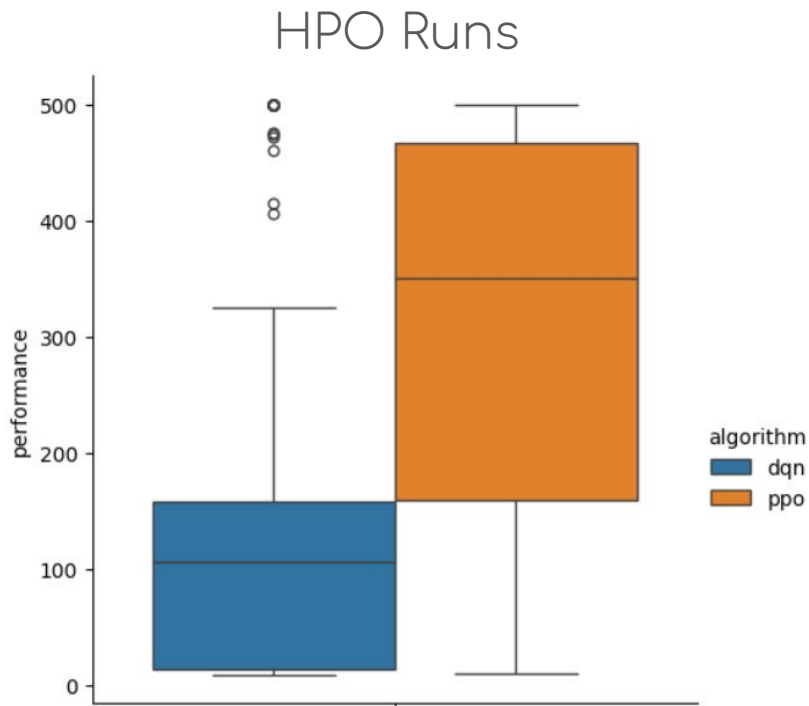
Definition: “difference between the risk of an overall reference configuration and the risk of the best possible configuration on that dataset”

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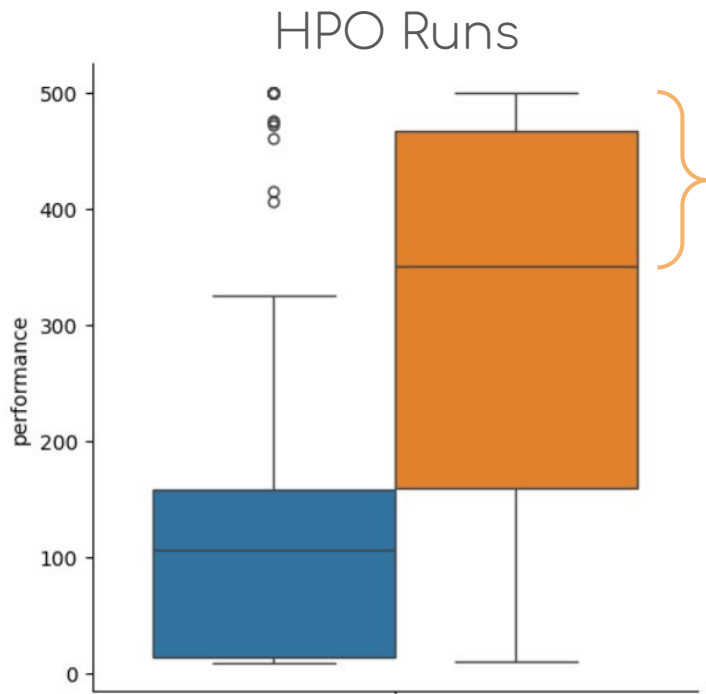
How well can the algorithm be adapted to different settings?

Example: PPO & DQN on CartPole

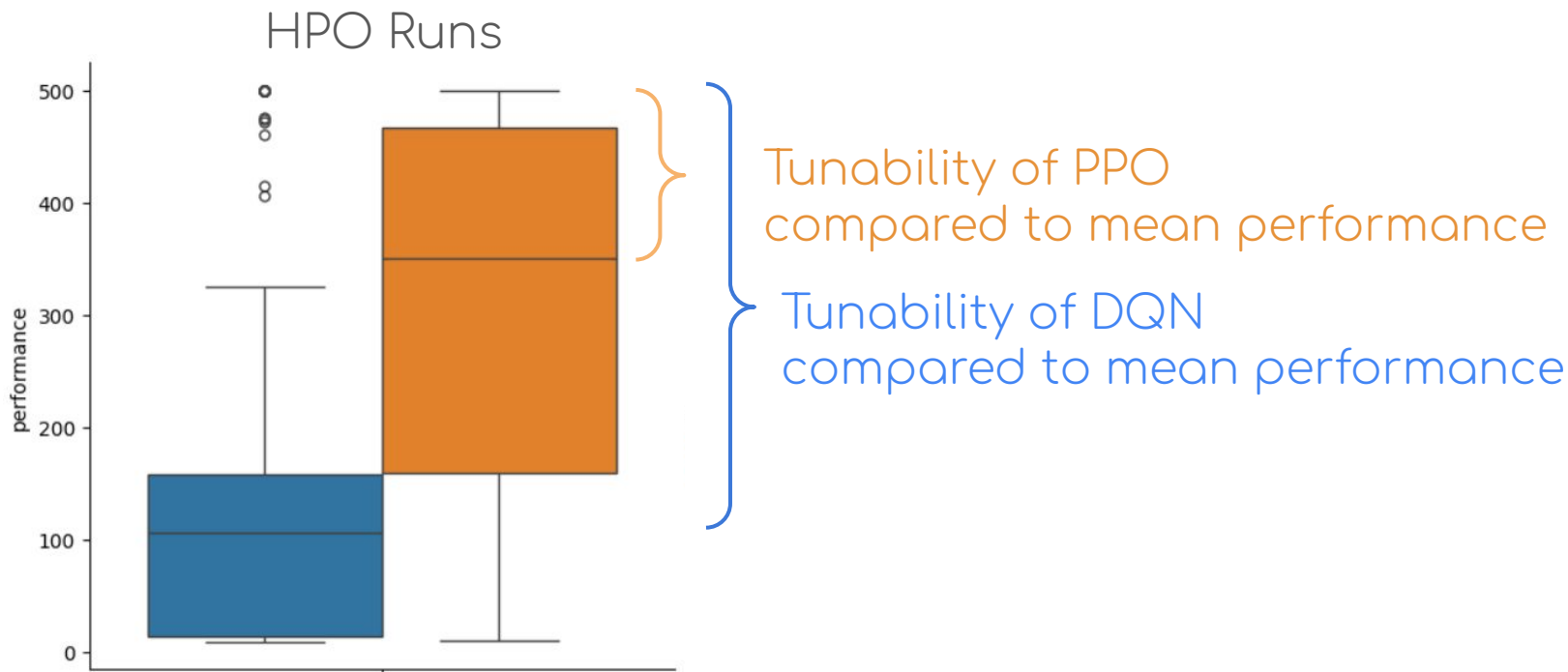


- Done with ARLBench [Becktepe & Dierkes et al. 2024]
- Tuning via Hypersweeper with SMAC [Lindauer et al. 2022]
- Budget: 32 full runs
- 1 run per configuration

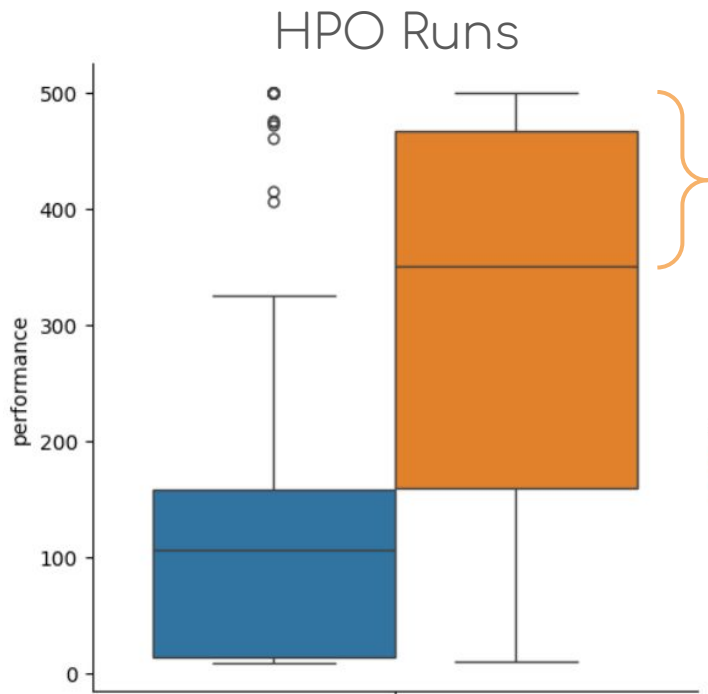
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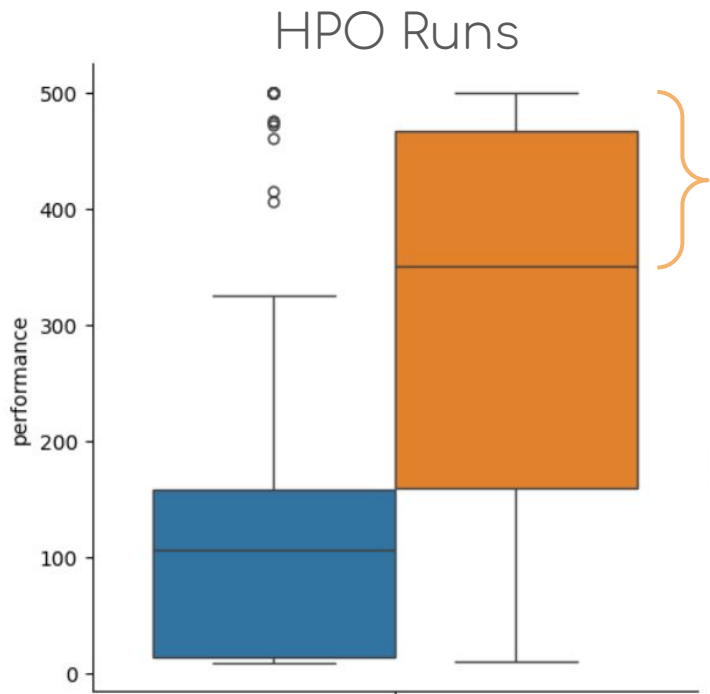


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Option 1: Algorithm is naturally good everywhere and doesn't need to be adapted

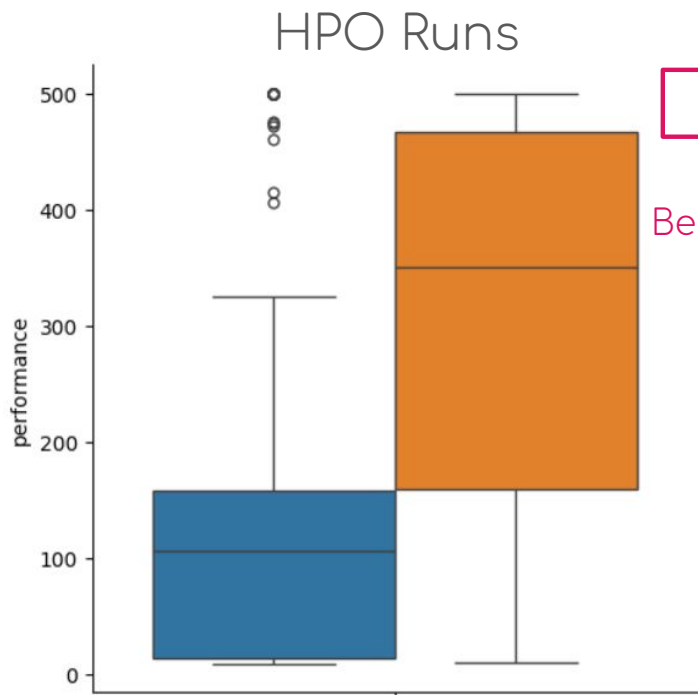
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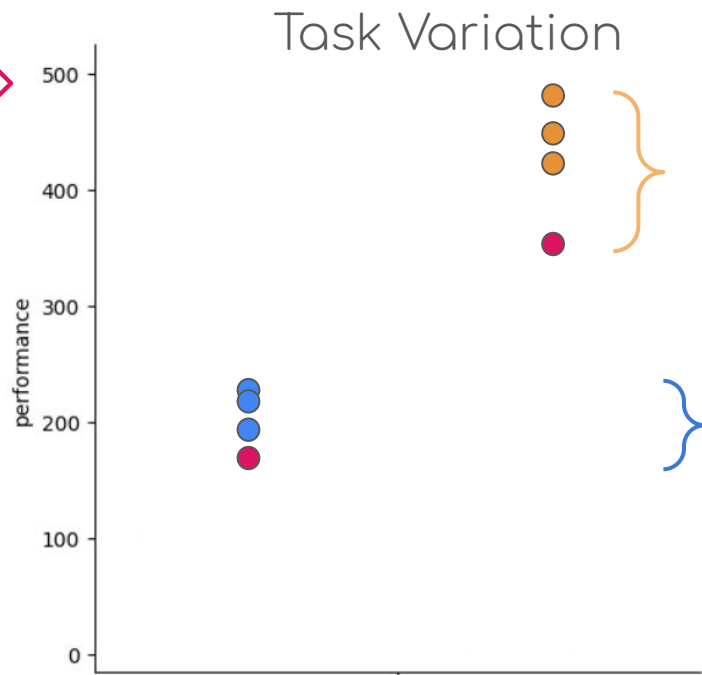
Option 1: Algorithm is naturally good everywhere and doesn't need to be adapted

Option 2: Algorithm is naturally okay everywhere but can't easily be adapted

Excursion: Tunability [Probst et al. 2019]



Best config

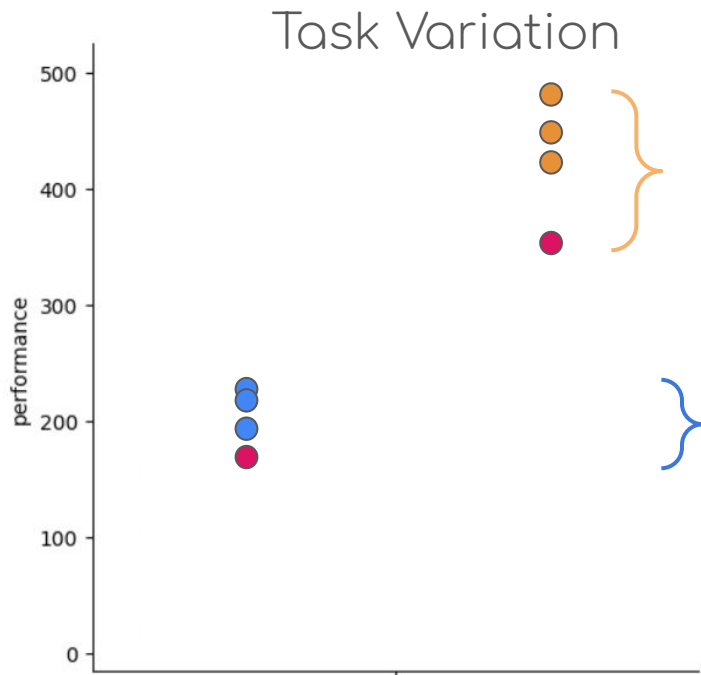


Excursion: Tunability [Probst et al. 2019]

Possible takeaways:

- Finding good HPs is easier in PPO
- On a task variation, it is faster to improve PPO

Application specialist: “PPO seems to be a better out of the box and I can get more out of it with only a few changes.”



What do we actually want to know?

RL algorithm researcher: “I want to know if the mechanics of this algorithm are good enough to solve RL problems generally”

Translation: algorithm is fixed, environment choice should support research question, reasonable experimentation budget

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Standard evaluation metrics like exploration coverage

Excursion: Tuning Efficiency

What does it mean if an algorithm is efficient to tune?

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What does it mean if an algorithm is efficient to tune?

- Few evaluations are enough to point to the optimum
- Random sampling likely yields good configurations
- It's clear early on if a configuration is good

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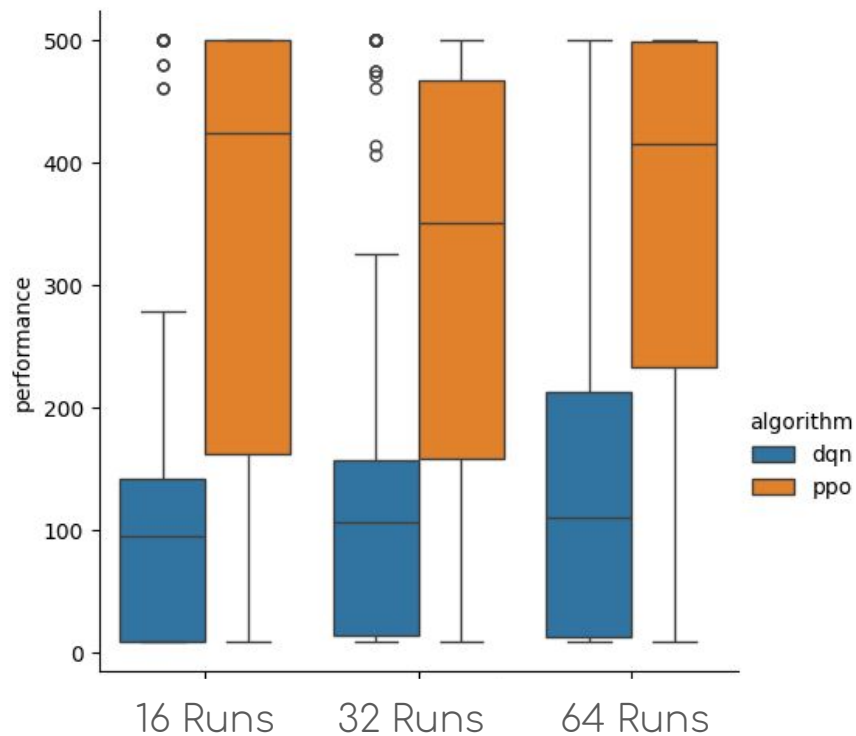
- Easily searchable, predictable performance landscape
- Much of the total configuration space has good performance
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Excursion: Tuning Efficiency

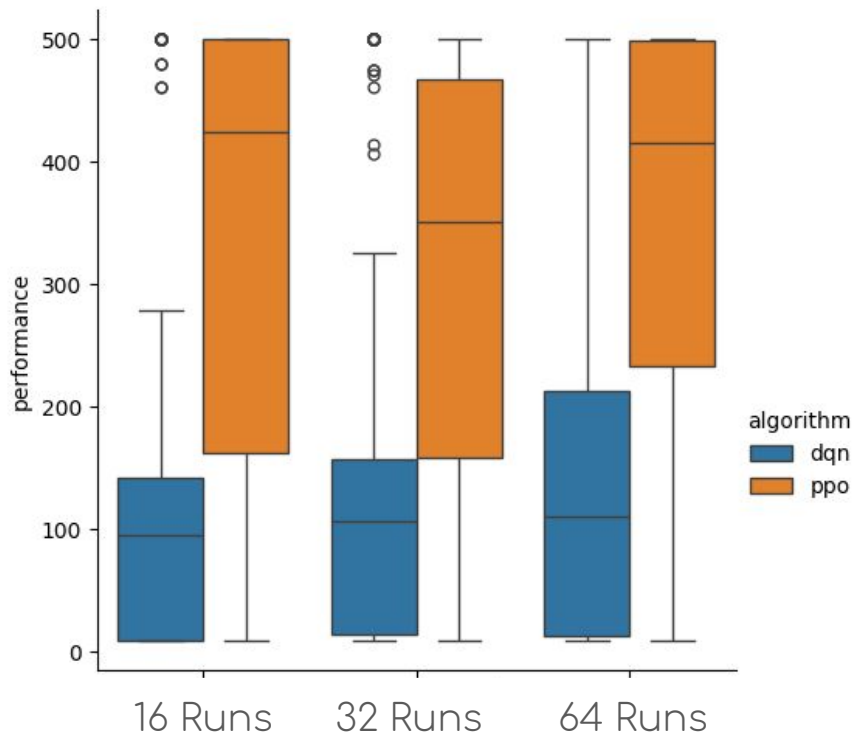
What does it mean if an algorithm is efficient to tune?

- Easily searchable, predictable performance landscape
- Much of the total configuration space has good performance
- High budget correlation

Example: PPO & DQN on CartPole



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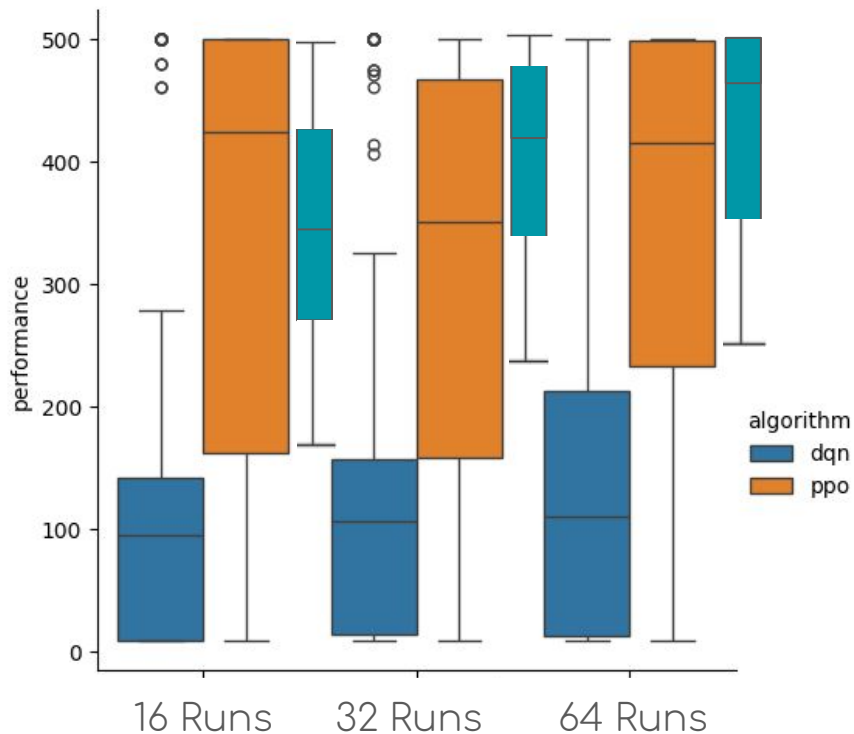


Possible takeaways:

- DQN responds predictably to search & more tuning effort
- PPO clearly has better average performance

RL algorithm researcher: “DQN is the more adaptable algorithm, but has poor default performance. If I can help it auto-adapt, I can get the best of both worlds.”

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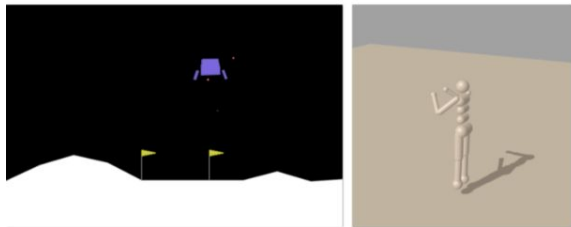
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Good tuning outcomes in the Algorithm Configuration Setting

Excursion: Algorithm Configuration [Schede et al. 2022]

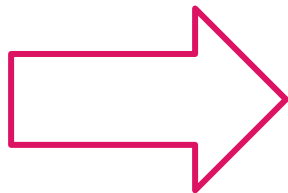
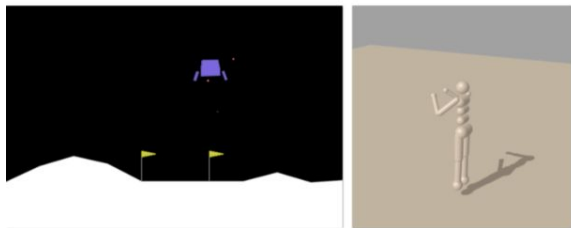
Tuning Environments



↑ Optimization ↓

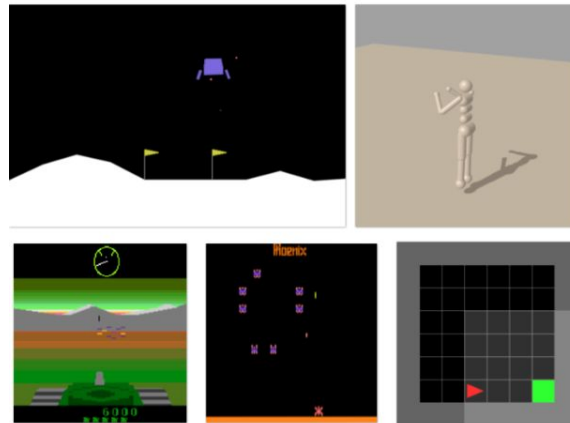
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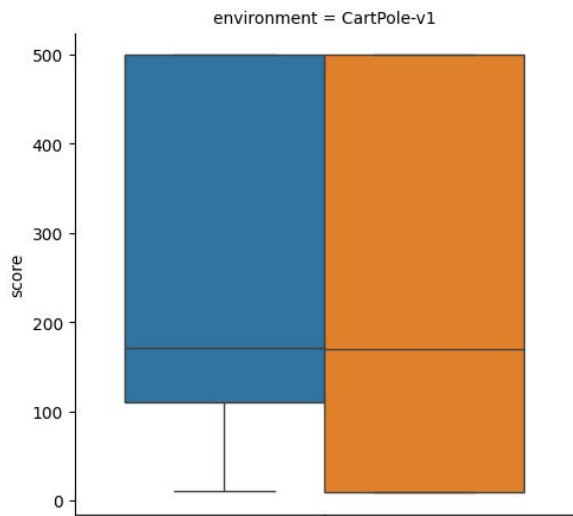
Best config

Test Environments

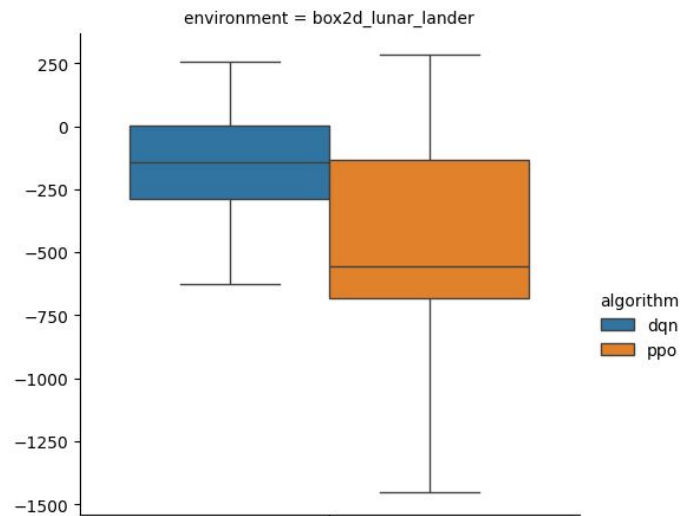
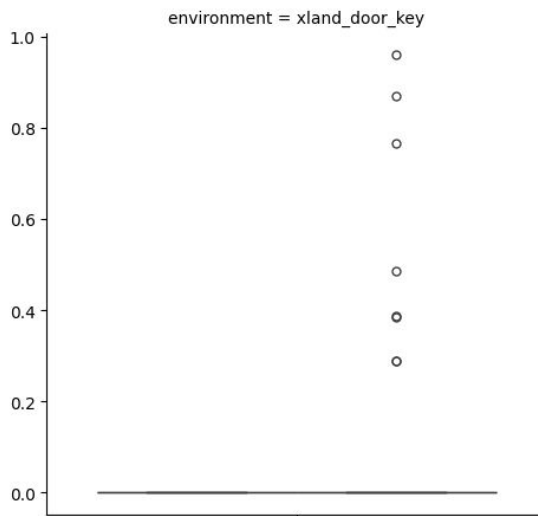


Example: PPO & DQN on CartPole

Tuned Environment



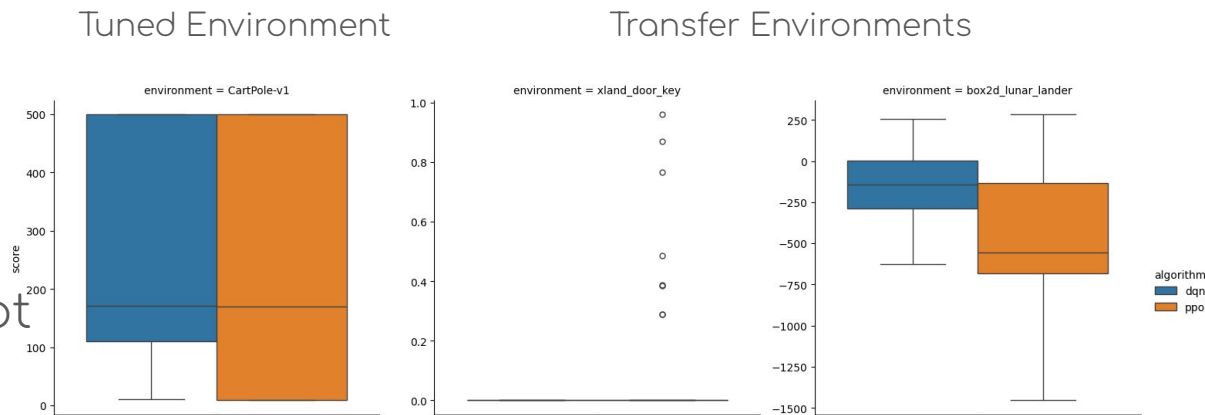
Transfer Environments



Example: PPO & DQN on CartPole

Possible takeaways:

- Both algorithms struggle in transfer
- Tuning on a single environment might not be enough



AGI enthusiast: “Currently none of these two algorithms are useful for me. I will have to try more extensive tuning or find an alternative.”

Framing 1: Complete Algorithms [Jordan et al. 2020]

Idea: All settings are considered part of the algorithm.

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Algorithm 1

DQN
ResNet-50
lr = 0.01

Algorithm 2

DQN
3-layer MLP
lr=0.005

...

Framing 1: Complete Algorithms [Jordan et al. 2020]

Idea: All settings are considered part of the algorithm.

Algorithm 1

DQN
ResNet-50
Random HPO

Algorithm 2

DQN
ResNet-50
HPO by BBO

...

Framing 1: Complete Algorithms [Jordan et al. 2020]

Idea: All settings are considered part of the algorithm.

Problems:

- Infinite amount of individual algorithms
- Not all algorithms vary in RL mechanics
- Difference being only e.g. network architecture or HPO can be interesting, but isn't always

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Advantage: Setting is now an essential part of the comparison

Framing 2: Randomization [Bouthillier et al. 2019]

Idea: Randomize settings to lower standard error

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Idea: Randomize settings to lower standard error

Standard

Random Seeds

More Random

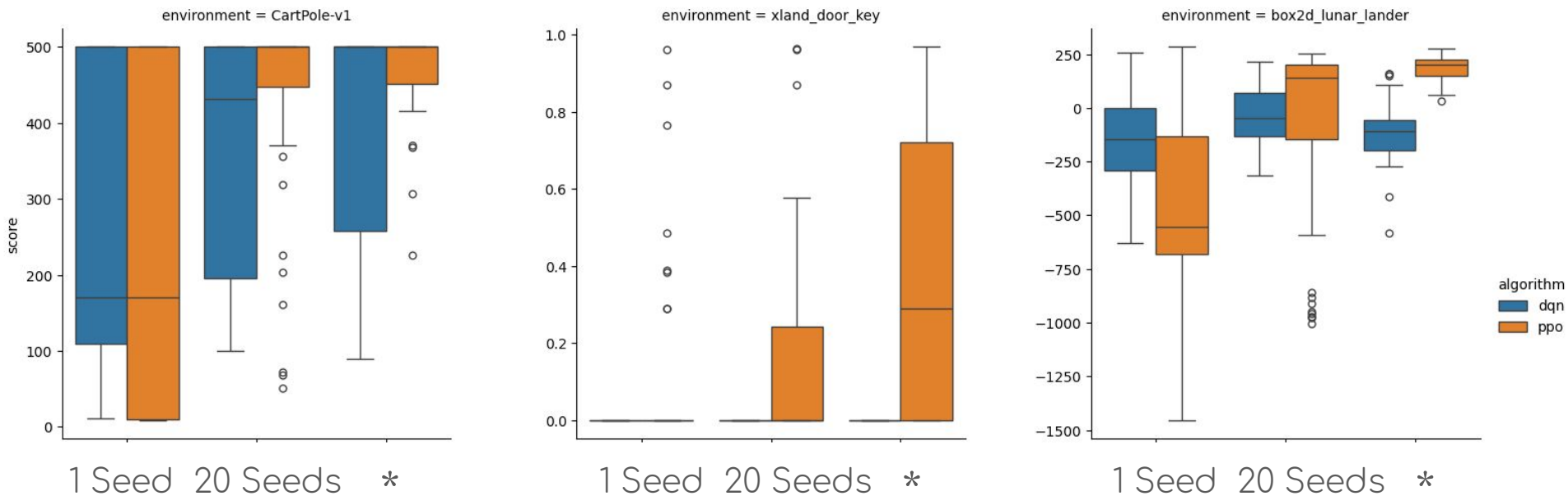
Random Seeds

Random Networks

Random n_envs

...

Example: PPO & DQN on CartPole



* Tuned across 20 Runs with randomly sampled seed, n_envs, hidden size & activation function

Framing 2: Randomization [Bouthillier et al. 2019]

Idea: Randomize settings to lower standard error

Problems:

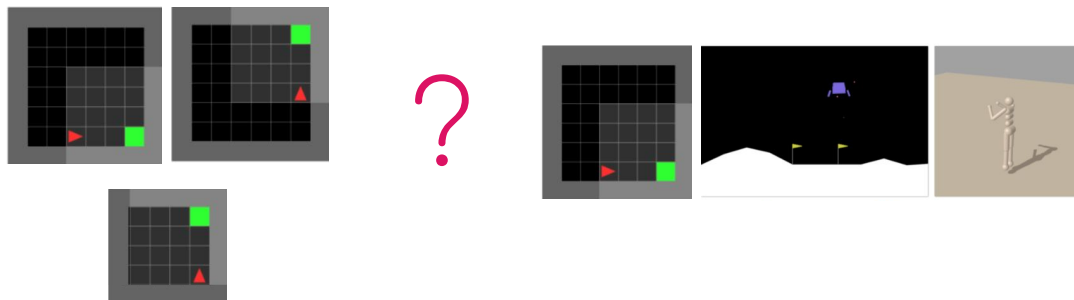
→ Randomizing relevant factors can cause higher variance

Framing 2: Randomization [Bouthillier et al. 2019]

Idea: Randomize settings to lower standard error

Problems:

- Randomizing relevant factors can cause higher variance
- Randomizing the environment can cause results to be extremely hard to interpret



So What Is The Best Framing?

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It doesn't exist!

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- Evaluation priorities should fit the research goals
- Exact setting and metrics depend on these priorities
- Standardized evaluation settings, HPO or metrics restrict expressiveness of our experiments

But What About Reproducibility?

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More expressive evaluations make the spirit of the results clearer

So What Evaluation Should I Use Now?

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→ Use existing protocols as templates

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Best practices

Standards for benchmarks

New research on evaluation practices

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- Consider non-standard metrics that support your goals

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Computational efficiency (e.g. wallclock time)

Generalizability across settings (e.g. random network architectures)

HPO metrics (e.g. tunability)

So What Evaluation Should I Use Now?

- Use existing protocols as templates
- Consider non-standard metrics that support your goals
- Show what sets your algorithm apart beyond just reward curves

Explicitly target a specific audience

Openly show Tradeoffs

Don't be afraid of making a contribution to a specific area rather than a very general improvement